

## 29624 - Control Engineering

### Información del Plan Docente

<b>Academic Year</b>	2016/17
<b>Academic center</b>	110 - Escuela de Ingeniería y Arquitectura
<b>Degree</b>	430 - Bachelor's Degree in Electrical Engineering
<b>ECTS</b>	6.0
<b>Course</b>	3
<b>Period</b>	First semester
<b>Subject Type</b>	Compulsory
<b>Module</b>	---

### **1.Basic info**

#### **1.1.Recommendations to take this course**

#### **1.2.Activities and key dates for the course**

### **2.Initiation**

#### **2.1.Learning outcomes that define the subject**

#### **2.2.Introduction**

### **3.Context and competences**

#### **3.1.Goals**

#### **3.2.Context and meaning of the subject in the degree**

#### **3.3.Competences**

#### **3.4.Importance of learning outcomes**

### **4.Evaluation**

### **5.Activities and resources**

#### **5.1.General methodological presentation**

This course is divided in two main parts: (1) digital control of continuous systems and (2) modeling, analysis and design of discrete event systems. The teaching process will involve three main activities : lectures , problems resolution and laboratory classes.

- During the lectures, theoretical and methodological concepts will be presented by using practical examples .
- During the problem resolution classes, different problems will be developed with the participation of students.
- Laboratory sessions will be developed individually or in groups of two students , where students will put into practice the concepts of interest , implement control systems on real systems and simulate using the computers the evolution of systems.

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### 5.2. Learning activities

The activities for the student include the following.

1) Lecture classes (type T1) (30 hours).

Lecture sessions of theoretical and practical content. The concepts of digital control of continuous systems and modeling, analysis and control of discrete event systems are introduced by using real examples. Student participation through questions and brief discussions is encouraged.

2) Classes of problems and resolution of use cases (type T2) (15 hours).

Problems and case studies with student participation, coordinated at all times with the theoretical contents are developed. Students are encouraged to work the problems previously.

3) Laboratory sessions (type T3) (15 hours).

The student performs simulation, design and implement control systems on real systems. The sessions consist in a preliminary study and a practical realization in the laboratory. The preliminary study should be done prior to practice.

4) Study (type T7) (86 hours).

Student personal study of theoretical concepts and implementation problems. The ongoing work of the student is encouraged by the homogeneous distribution throughout the semester of the various learning activities. This includes tutorials, as a direct student care, identification of learning problems, guidance on the subject, attention to exercise and doubts.

5) Evaluation exams (T8) (4 hours).

In addition to the qualifying function, evaluation is also a learning tool with which the student checks the degree of understanding and assimilation reached.

### 5.3. Program

The course contents are:

• Topic 1: Introduction

• Topic 2: Digital control of continuous systems

Discrete-time signals

Z transform: definition, properties, tables

Description of sampled systems

Discretization of continuous systems

Sampled Systems Analysis

Design of digital controllers

Practical aspects of implementation

• Topic 3: Discrete (event) systems

Preliminary considerations and definition

Formalisms to represent the DES and interest in engineering

Deterministic Finite Automaton (DFA)

Mealy and Moore models. Transformations and minimization

Limitations of DFA

Petri nets

Concept, typical structures and modeling methodology

Some properties, analysis and implementation techniques

Laboratory sessions to be performed:

• Digital control of a servomechanism (discretization of continuous controllers).

• Digital control of a servomechanism (direct design).

• Control of a discrete event system (DFA implementation).

• Control of a flexible manufacturing cell (Petri net implementation).

• Analysis of discrete systems in MATLAB

### 5.4. Planning and scheduling

All classes are scheduled by EINA and are available on its website (<https://eina.unizar.es/>).

Each teacher publish its schedule of office hours .

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The other activities are planned depending on the number of students and are available at <http://add.unizar.es>

### 5.5. Bibliography and recommended resources

*Bibliography* can be found in <http://psfunizar7.unizar.es/br13/eGrados.php?id=220>

The following books can be used by the students.

#### 1. Introducción.

- Aström and Murray: Feedback Systems: An Introduction for Scientists and Engineers, Princeton University Press, disponible online [http://www.cds.caltech.edu/~murray/amwiki/Main\\_Page](http://www.cds.caltech.edu/~murray/amwiki/Main_Page)

#### 2. Control de sistemas en tiempo discreto.

- Smith and Corripio: Principles and Practice of Automatic Process Control, 2nd edition, Wiley and Sons - Capítulo 14.
- Moreno, Garrido y Balaguer; Ingeniería de Control; Ariel Ciencia - Capítulo 6.

#### 3. Sistemas de eventos discretos

- Cassandras, C.G. & S. Lafortune: Introduction to Discrete Event Systems, Springer, 2008.
- Silva Suárez, M.: Las redes de Petri en la automática y la informática, Madrid, Editorial AC 1985 (reimp. Madrid, Thomson-AC, 2002).