

ANEXOS



ANEXO A

PLATAFORMA MOOG 6DOF2000E



Series 6D0F2000E

Electric Motion Platform



> 6 Degrees of Freedom

> 1000 Kg Payload /2200 lbs

- > Integrated Design
- > Electric Actuation





Cabin images courtesy of AITEC GmbH & SimEx Inc.

Worldwide Support

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Europe:

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Moog Sarl, Cedex, France • Telephone: +33(0)1 45607000 • Fax: +33(0)1 45607001

Moog Sarl Sucursal En España, Orio, Spain • Telephone: +34(0)9 43133240 • Fax: +34(0)9 43133180

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Moog Australia Pty. Ltd., Mulgrave, Australia • Telephone: +61(0)3 9561-6044 • Fax: +61(0)3 9562-0246 Moog Japan Ltd., Hiratsuka, Japan • Telephone: +81(0)463-55-3615 • Fax: +81(0)463-54-4709

Series 6D0F2000E

Moog Inc.

Moog Motion Systems offer high performance solutions to motion simulator requirements. Fifty years of experience and a proven track record makes Moog the world's leading supplier of motion system components and integrated platforms in both the training and entertainment markets.

Moog produces both 4 degree and 6 degree of freedom (DOF) motion bases, with actuator strokes ranging from 12 to 62 inches and load capacities up to 14,600 Kg (32,200 lbs).

Specifications: 6DOF2000E Size:

Settled Height	0.71 m (28")
Foot Print	≈1.84 m (w) x 1.84 m
	(≈72.5" (w) x 72.5")
Std. Flying Floor	
Structural Triangle	≈ 1.5 m (59") per side
System Weight	

Facility:

Average Floor Loadin	g
Compression	1900 Kg/m ²
Compression	(380 lb/ ft²)
Power	, , ,
Control	1ø, 100-120 vac.
	50-60 Hz
	10 Amp service
Main	
	50-60 Hz
	20/30 Amp service

Load:

Max. Customer Payload	l1000 Kg (2205 lbs)
CG Location	
Horizontal	≤ 0.06 m (2.5")
(from centroid)	
Vertical	≤ 0.6 m (24")
(above the top of fly	ing platform)
Motion Centroid	0.13m (5.1")
(below the top of fly	ing platform)
Mass Moment of Inert	
Pitch Axis	650 Kg-m ²
	(5750 in-lb-sec²)
Roll Axis	400 Kg-m ²
	(3540 in-lb-sec ²)
Yaw Axis	650 Kg-m ²
	(5750 in-lb-sec²)

Actuator Features:

- DC Servomotor
- Fold-back design for low boarding height and efficient field service
- Low friction actuator using precision ballscrew design
- Internal hydraulic snubbers for end of stroke cushioning
- Encoder feedback
- End of stroke limit switches
- Actuator brakes available for "freeze mode"/E-stop circuit

Documentation:

- Facility Requirements
- Installation Instructions
- Operation/Maintenance Manual

Reliability:

- Custom high efficiency drives and actuators optimized for performance and long life in demanding applications. Designed for a minimum 5 year life.
- Detailed fault tree analysis for all single point and multiple failure modes has been performed.
- Drives have been life cycle tested and have proven field history.

Field Service and Repair:

- One (1) year part warranty from the date of shipment
- Worldwide support
- Installation and training support provided

Compliance:

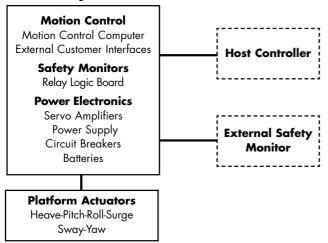
- The system is designed to U.S. and European electrical codes.
- The system utilizes UL and CE compliant components.
- Designed to meet the AFGS-87241A requirement to egress to home position in event of major single point failures.
- Electronics are CE marked

Interface Options:

Serial Interface (R\$-485)

- Ride Storage
- Real Time (non-ride storage) Ethernet Interface
- Real Time
- Real Time with Motion Cueing (Motion Dynamics Algorithm)

Motion System Interfaces:



Motion:

Degree of Freedom	Displacement Comb. Motion	Displacement Single DOF	Velocity	Acceleration
Pitch	+25/-23 deg	±22 deg	±30 deg/s	±500 deg/s ²
Roll	±22 deg	±21 deg	±30 deg/s	±500 deg/s ²
Yaw	±23 deg	±22 deg	±40 deg/s	±400 deg/s ²
Heave	±0.18 m (±7.0 in)	±0.18 m (±7.0 in)	±0.30 m/s (±11.8 in/s)	+0.5 g
Surge	±0.27 m (±11.1 in)	±0.25 m (+10.2/-9.5in)	±0.50 m/s (±19.7 in/s)	±0.6 g
Sway	±0.26 m (±11.7in)	±0.25 m (±10.2 in)	±0.50 m/s (±19.7 in/s)	±0.6 g

Specifications are subject to change without notice





CHAPTER 3.0

ETHERNET COMMUNICATIONS PROTOCOL

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3.5 DOF MODE COMMAND (SCC to MB)

Figure 3-7 shows the format for the 8 word DOF Mode command. For the DOF mode, DOF commands (words 1 through 6) are all 32 bit float values. Values for the platform angles / position are defined in radians (rad) or meters (m). The values given in Figure 3-7 are assumed to be in host byte order (LSB first).

Software Limits for Degrees of Freedom: Refer to section 6.2.

#	Data	Description	Unit	Туре
0	MCW	Motion Command Word	-	32 bit unsigned long
1	roll	Roll Command	rad	32 bit float
2	pitch	Pitch Command	rad	32 bit float
3	position_z	Heave Command	m	32 bit float
4	position_x	Surge Command	m	32 bit float
5	yaw	Yaw Command	rad	32 bit float
6	position_y	Lateral Command	m	32 bit float
7	-	Spare	-	32 bit tbd

Figure 3-2: DOF Mode Command



CHAPTER 3.0

ETHERNET COMMUNICATIONS PROTOCOL

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8 WORD COMMAND DATAPACKET (SCC TO MB) - DOF MODE

WORD	DESCRIPTION	<u>FORMAT</u>
		d31 d0
0	MOTION COMMAND WORD (LSB holds command byte)	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
	(202	
	DISABLE 220 (DC HEX)	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
	PARK 210 (D2 HEX)	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
	LOW LIMIT ENABLE 200 (C8 HEX)	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
	LOW LIMIT DISABLE 190 (BE HEX)	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
	ENGAGE 180 (B4 HEX)	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
	START 175 (AF HEX)	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
	LENGTH MODE 172 (AC HEX)	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
	DOF MODE 170 (AA HEX)	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
	RESET 160 (A0 HEX)	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
	INHIBIT 150 (96 HEX)	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
	MDA MODE 140 (8C HEX)	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
	NEW POSITION 130 (82 HEX)	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
1	ROLL COMMAND	xxxxxxxxxxxxxxxxxxxxxxxxxxx
2	PITCH COMMAND	××××××××××××××××××××××××××××××××××××××
3	HEAVE COMMAND	x x x x x x x x x x x x x x x x x x x
4	SURGE COMMAND	x x x x x x x x x x x x x x x x x x x
5	YAW COMMAND	x x x x x x x x x x x x x x x x x x x
6	LATERAL COMMAND	x x x x x x x x x x x x x x x x x x x
7	SPARE	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0

X = AS REQUIRED



CHAPTER 3.0

ETHERNET COMMUNICATIONS PROTOCOL

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3.7 COMMANDS (SCC to MBC)

Command values are all 8 bit unsigned long values sent to the MB computer in byte ϕ of word 0 of the command datapacket data area. The decimal value assigned to each command is placed in the LSB of the command word.

WARNING: THE SYSTEM INTEGRATOR OF THE MOTION BASE IS RESPONSIBLE FOR CONNECTING THE MOTION BASE E-STOP CIRCUIT DESCRIBED IN THE 6DOF2000E USER'S MANUAL. THE COMMUNICATIONS E-STOP COMMAND IS NOT INTENDED TO REPLACE THIS SAFETY FEATURE.

3.7.1 220: DISABLE (Valid in any state)

- 1) The MB disables Ethernet communications, ignoring further commands;
- 2) removes power from the motor controllers;
- 3) returns to HOME position under battery power.

Reset is manual (remove & re-apply power to MB).

3.7.2 210: PARK (Valid only in ENGAGED, STANDBY states)

MB returns to PARK position under power, then removes power from the motors.

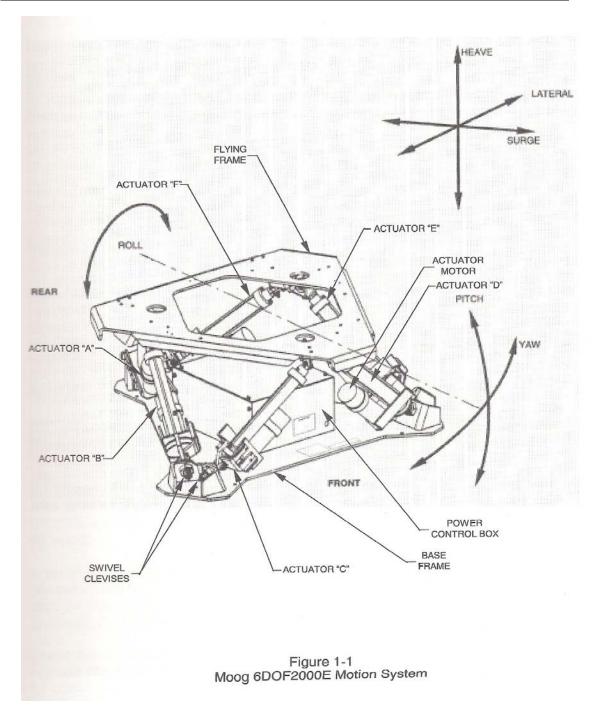
3.7.3 200: LOW LIMIT ENABLE (Valid in all states)

Tells MB software to remove the low limit shunt (see next command description). The SCC does not need this command in normal operation.

3.7.4 190: LOW LIMIT DISABLE (Valid in all states)

Shunts the limit switches so that limit faults and amplifier faults cannot be detected. The MB software controls the shunt automatically at ride startup and when parking, so the SCC should not need to use this command except possibly in a maintenance mode. The shunt is removed automatically by the MB software after 2 seconds in the ENGAGED state (refer to later sections on MB operation).







CHAPTER 3.0 ETHERNET COMMUNICATIONS PROTOCOL

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3.7.5 180: ENGAGE (Valid only in the IDLE state)

Makes MB ready to run (applies power to the motor controllers). To engage, communications must be OK, machine state must be idle, and the base must be "at home".

Actuator commands must be:

Length mode - all lengths at 0.03048m

DOF mode - all DOFs must be = 0.0 m or 0.0 rad

MDA mode - all command data must = 0.0

The MBC software powers and enables the amplifiers, then moves the base up to the starting position listed above. At this point the machine state becomes ENGAGED, and the customer's SCC can control the actuator movement. The SCC must keep the command data at these values until the base is ENGAGED to avoid abrupt motions.

3.7.6 175: START (Valid only in the IDLE state)

Same as ENGAGE, except the customer may define the starting position of the base. Valid start positions ranges are:

- Length mode lengths from 0.03048m to 0.30988m
- DOF mode all commands must be at neutral = 0.0m or 0.0 rad, except for heave, which may range from 0.0m to -0.4572m
- MDA mode START command not valid in MDA mode

In the Length and DOF modes, words 1 through 6 indicate the start position. These words must not change until after the base has reached the ENGAGED state to avoid abrupt motions when the base becomes ENGAGED.

3.7.7 172: LENGTH MODE (Valid only in the IDLE, POWERUP states)

Commands MB to interpret the actuator command data as actuator lengths from 0.03048m to 0.30988m.

3.7.8 170: DOF MODE (Valid only in the IDLE, POWERUP states)

Advises MB to interpret the actuator command data as degrees of freedom. Data is ordered as roll, pitch, heave, surge, yaw, sway, in the command frame. For the DOF mode, DOF commands are all 32 bit float values. Values for the platform angles / position are defined in radians (rad) or meter (m). DOF mode is the default mode of MB operation.



PTER 3.0

ETHERNET COMMUNICATIONS PROTOCOL

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160: RESET (Valid in FAULT & INHIBIT states)

to recover a MB from FAULT_2 state; also restores normal operation after NHIBIT command is received.

0 150: INHIBIT (Valid in POWER UP, IDLE states)

nporary means of de-activating the MB. The MB ignores further commands the RESET command is received.

1 140: MDA MODE (Valid only in the IDLE, POWERUP states)

ses MB to interpret the acceleration and angular rate data. For the MDA DOF commands are all 32 bit float values. Values for the accelerations, tefined in radians per (second x second) (rad/s²) or meters per (second x nd) (m/s²). Values for the velocities are defined in radians per second (rad/s) eters per second (m/s). Values for the lengths or angles, are defined in ns (rad) or meters (m). The MB must be purchased with MDA mode rare option in order to enter MDA mode.

2 130: NEW POSITION (may be sent in any state)

des position command data (lengths or DOFs) to the MB. The MB in the AGED state will update its position loops with the data provided in the nand frame. Not valid in MDA mode.

3 128: NEW MDA (may be sent in any state) (MDA mode only)

des acceleration and specific force command data to the MB. The MB in the AGED state will update its position loops with the data provided in the nand datapacket. Not valid in DOF or Length modes.

4 155: NEW MDA FILE (Valid only in IDLE, POWERUP states)

lests the MB to change the MDA tuning file from the default value (which is The tuning file will be changed if the requested file exisits. The MDA onse datagram will indicate which MDA file number is being used.



CHAPTER 6.0

6DOF2000E PHYSICAL DATA

6-1

CHAPTER 6.0 6DOF2000E PHYSICAL DATA

6.1 PURPOSE

The purpose of this chapter is to provide excursion limits of the MB in terms of linear measurement, 32-bit float values and degrees of freedom.

6.2 6DOF2000 PHYSICAL DATA

All length measurements are referenced from the actuator full-retracted position.

0	Maximum physical actuator stroke	0 to0.34036m (0 to13.4 in.)
	Extend limit switch position	0.32385m (12.75 in.)
•	Retract limit switch position	0.01905m (0.75 in.)
•	Software extend limit (max useable stroke)	0.30988m (12.2in.)
	Software retract limit (min useable stroke)	0.03048m (1.2 in.)

Software Limits for Degrees of Freedom:

NOTE:

THESE DOF LIMITS ARE USED TO SCALE INCOMING COMMANDS, AND DO NOT IMPLY THAT THE 6DOF2000E MOTION BASE IS CAPABLE OF MOVING TO THESE VALUES. REFER TO THE 6DOF2000E SPECIFICATIONS FOR ACTUAL MOTION CAPABILITIES.

	MIN	MAX
Roll (rad)	.50605	+0.50605
Pitch (rad) 0		+0.57585
Heave (m) 0.		-0.4572
Surge (m)		+0.38100
Yaw (rad)	.50605	+0.50605
Lateral (m) - 0		+0.38100

DOF orientations are defined from the perspective of a rider seated on the base facing forward, refer to Figure 6-1, Moog 6DOF2000E Motion System DOF's:

- ROLL: positive means right edge of platform goes down, left edge moves up.
- PITCH: positive, front edge of platform moves up, rear edge moves down.
- HEAVE: positive means entire platform moves down.
- SURGE: positive means entire platform moves forward.
- YAW: positive means platform rotates clockwise as viewed from above.
- LATERAL: positive means platform moves to the right.



ANEXO B

ORDENADOR Y JOYSTICK



Características

- Procesador Intel Core 2 Duo E6750 @ 2.66 GHz
- 3 GB de Memoria RAM
- GeForce 8800 GT 512 Mb
- Joystick de 8 botones y throttle analógico Microsoft Sidewinder



Figura B.1 Microsoft Sidewinder Joystick



ANEXO C

SENSORES

Model 87N UltraStableTM





- 316L SS Pressure Sensor
- High Pressure
- 0 100mV Output
- Absolute and Sealed Gage
- Temperature Compensated

DESCRIPTION

The Model 87N UltraStable™ is a small profile, media compatible, piezoresistive silicon pressure sensor packaged in a 316L stainless steel housing. The Model 87N UltraStable™ is offered in a weldable package or with a variety of threaded fittings such as 1/4 and 1/8NPT, 1/4BSP as well as custom process fittings.

The Model 87N UltraStable™ is designed for high pressure OEM applications where compatibility with corrosive media is required. The sensing package utilizes silicon oil to transfer pressure from the 316L stainless steel diaphragm to the sensing element. A ceramic substrate is attached to the package that contains laser-trimmed resistors for temperature compensation and offset correction. An additional laser trimmed resistor is included which can be used to adjust an external differential amplifier and provide span interchangeability to within ±1%.

FEATURES

- Weldable and Threaded Process Fittings
- -20°C to +85°C Compensated Temperature Range
- ±0.25% Pressure Non Linearity
- 1.0% Interchangeable Span (provided by gain set resistor)
- Solid State Reliability

APPLICATIONS

- Hydraulic Controls
- Process Control
- Pressure Calibrators
- Refrigeration/Compressors

STANDARD RANGES

Range	psia	psis
0 to 1000	•	•
0 to 3000	•	•
0 to 5000	•	•

Model 87N UltraStableTM



PERFORMANCE SPECIFICATIONS

Supply Current: 1.5mA

Ambient Temperature: 25 °C (unless otherwise specified)
Parameters are specified for the compensated versions only

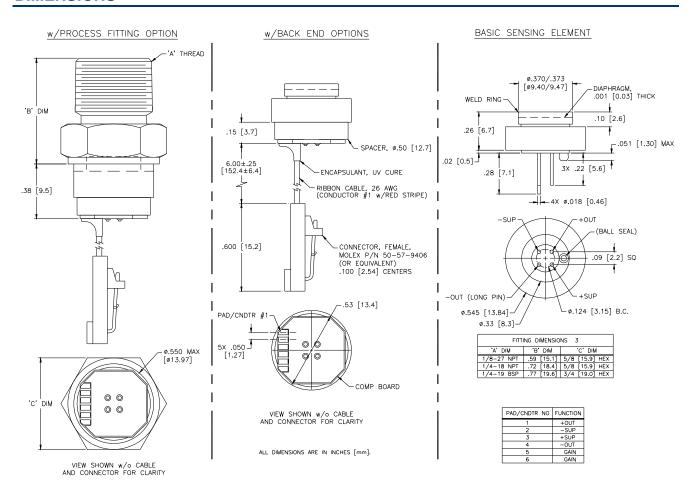
PARAMETERS	MIN	TYP	MAX	UNITS	NOTES
Span	75	100	150	mV	1
Zero Pressure Output	-1		1	mV	
Pressure Non Linearity	-0.25		0.25	%Span	2
Pressure Hysteresis		±0.05		%Span	
Repeatability		±0.02		%Span	
Input Resistance	2000	2750	4000	Ω	
Output Resistance	4000		25k	Ω	
Temperature Error – Span	-0.75		0.75	%Span	3
Temperature Error – Offset	-0.75		0.75	%Span	3
Thermal Hysteresis – Span		±0.05		%Span	3
Thermal Hysteresis – Offset		±0.05		%Span	3
Long Term Stability – Span		±0.1		%Span	4
Long Term Stability - Offset		±0.1		%Span	4
Supply Current	0.5	1.5	2.0	mA	
Insulation Resistance (50Vdc)	50			ΜΩ	5
Pressure Overload			3X	Rated	6
Compensated Temperature	-20		+85	ōC	
Operating Temperature	-40		+125	ōC	7
Storage Temperature	-50		+125	ōС	7
Weight			9	grams	
Media – Pressure Port	Liquids and Gas	ses compatible wi	th 316L Stainless S	Steel	

Notes

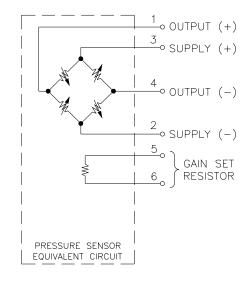
- 1. Ratiometric to supply current.
- Best fit straight line.
- 3. Maximum temperature error between -20 °C and +85 °C with respect to 25 °C.
- 4. Long term stability over a one year period with constant current and temperature.
- 5. Minimum resistance between case and pins.
- 6. 2X maximum for 5000 psi devices.
- 7. Maximum temperature range for product with standard cable and connector is -20 °C to +105 °C.



DIMENSIONS

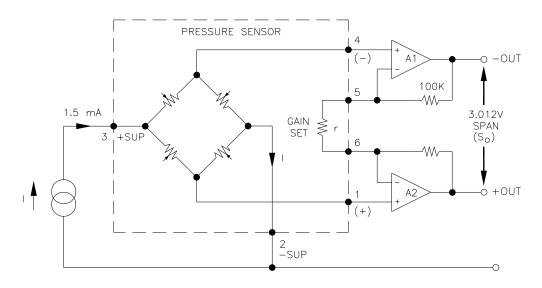


CONNECTIONS



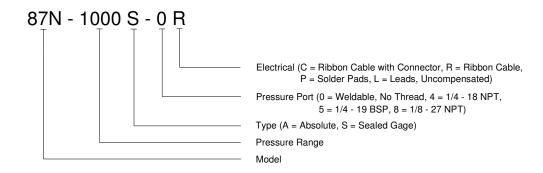


APPLICATION SCHEMATIC



APPLICATION SCHEMATIC

ORDERING INFORMATION



NORTH AMERICA

Measurement Specialties 45738 Northport Loop West Fremont, CA 94538 Tel: 1-800-767-1888

Fax: 1-510-498-1578

Sales: pfg.cs.amer@meas-spec.com

EUROPE

Measurement Specialties (Europe), Ltd. 26 Rue des Dames 78340 Les Clayes-sous-Bois, France Tel: +33 (0) 130 79 33 00

Fax: +33 (0) 134 81 03 59

Sales: pfg.cs.emea@meas-spec.com

ASIA

Measurement Specialties (China), Ltd.
F1.6-4D, Tian An Development Compound
Shenzhen, China 518048

Tel: +86 755 8330 1004 Fax: +86 755 8330 6797

Sales: pfg.cs.asia@meas-spec.com

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9 mm Square Rotary Potentiometers with Insulated Shaft

Type: **EVUE/EVUF**

Features

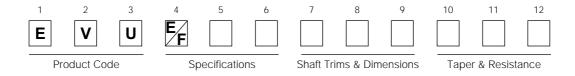
- Multi-gang block can be provided upon request
- DC voltage available
- Rigid rectangular shape suited for automatic insertion

■ Recommended Applications

- Audio Equipment
- Video Equipment
- Electronic Musical Instruments
- Audio Mixers

Malaysia

■ Explanation of Part Numbers



Japan

■ Product Chart

Construction	Style	Height (H=mm)	Detent	Туре
		/ F	Without detent	EVUE20
		6.5	Midpoint	EVUE30
	Without bushing	10.0	Without detent	EVUE2A
	Without bushing	10.0	Midpoint	EVUE3A
		12.5	Without detent	EVUE21
		12.5	Midpoint	EVUE31
Horizontal		6.5	Without detent	EVUE25
ПОПZОПІЛІ	With bushing	0.5	Midpoint	EVUE35
	With bushing	10.0	Without detent	EVUE2J
		10.0	Midpoint	EVUE3J
		6.5	Without detent	EVUE27
	With sleeve	0.5	Midpoint	EVUE37
	With Sieeve	10.0	Without detent	EVUE2K
		10.0	Midpoint	EVUE3K
	Without bushing		Without detent	EVUF2A
	Williout bushing	_	Midpoint	EVUF3A
		7.5	Without detent	EVUF2J
	With bushing	7.5	Midpoint	EVUF3J
Vertical	With bushing	8.5	Without detent	EVUF2M
vertical		0.0	Midpoint	EVUF3M
		7.5	Without detent	EVUF2K
	With sleeve	7.0	Midpoint	EVUF3K
	willi Sieeve	8.5	Without detent	EVUF2L
		0.0	Midpoint	EVUF3L

Panasonic

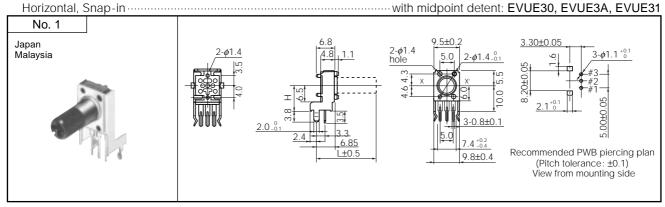
■ Specifications

Classification	Item	Type without bushing	Type wit	h bushing	Type wi	th sleeve
	Rotation Angle		30	00°	1	
	Rotation Torque	1 mN·m to 8 mN·m (after rotation started) 1 mN·m to 20 mN·m	(after rotation started)	1 mN·m to 20 mN·m	(after rotation started)
	Shaft Stopper Strength		300	mN·m	1	
		• Shaft bend and shaft wobble shall b $0.8 \times \frac{L}{20}$ (mm) max. (for one side)	1 .	shaft wobble shall be max. (for one side)	1	shaft wobble shall be max. (for one side)
Mechanical Specifications	Shaft wobble	When moment of 25 mN·m is applied.	When mo 50 mN⋅m	is applied.	(When mo 50 mN·m	is applied.
		 L=Distance between mounting surface and measuring point 		etween mounting neasuring point	 L=Distance be surface and m 	etween mounting neasuring point
	Shaft Pull/Push Strength	Push strength Pull strength 100 N min. 100 N min.	Push strength 100 N min.	Pull strength 100 N min.	Push strength 100 N min.	Pull strength 100 N min.
	Nut Tightening Torque	_	1 N·n	n max.		_
	Nominal Total Resistance	1 k Ω to 1 M Ω , 300 k Ω to	2 M Ω for taper	B (Tolerance	±20 %)	
	Taper	A, B, C, D, G				
	Power Rating					
	January Company	be derated in accordanc	_	Rated	20	40 60 70 perature(*C)
Electrical Specifications		be derated in accordanc	e with the figur	e < 50 kΩ e < 1 MΩ	0 20 Ambient Tem	perature(°C) ! max. ! max.
	Residual Resistance	be derated in accordanc on the right.	e with the figur $\frac{R}{50~\text{k}\Omega} < R$	e < 50 kΩ e < 1 MΩ	$\begin{array}{c c} 20 & & & \\ 0 & 20 & \\ \text{Ambient Tem} \end{array}$	perature(°C) ! max. ! max.
		be derated in accordance on the right.	e with the figur R $50 \text{ k}\Omega < R$ $1 \text{ M}\Omega < R$ A, B, D, G $T1 \text{ & T2}$ 2Ω	$\begin{array}{c} < 50 \text{ k}\Omega\\ < 1 \text{ M}\Omega\\ < 2 \text{ M}\Omega\\ \end{array}$ B, C, G T2 & T3 max.	20 Ω 20 Ambient Tem 50 Ω 100 Ω 200 Ω A, D T2 & T3 20 Ω	e max. e max. e max. c max. C T1 & T2
		be derated in accordance on the right.	e with the figur $\frac{R}{50 \text{ k}\Omega < R}$ $\frac{50 \text{ k}\Omega < R}{1 \text{ M}\Omega < R}$ $\frac{A, B, D, G}{T1 \text{ & T2}}$ $\frac{2 \Omega}{2 \Omega}$	$\begin{array}{c} < 50 \text{ k}\Omega \\ < 1 \text{ M}\Omega \\ < 2 \text{ M}\Omega \\ \end{array}$ B, C, G T2 & T3 max.	20 0 20 0 0 0 0 0 0 0 0 0	e max. e max. c max. C T1 & T2 e max. e max.
		be derated in accordance on the right.	e with the figur $\frac{R}{50 \text{ k}\Omega < R}$ $\frac{50 \text{ k}\Omega < R}{1 \text{ M}\Omega < R}$ $\frac{A, B, D, G}{T1 \text{ & T2}}$ $\frac{2 \Omega}{2 \Omega}$	< 50 kΩ < 1 MΩ < 2 MΩ < 2 MΩ B, C, G T2 & T3 max. max. max.	20 0 20 0 0 0 0 0 0 0 0 0	e max. e max. c max. C T1 & T2 e max. e max. e max. c max. e max. e max. e max. e max. e max.
		be derated in accordance on the right.	e with the figur $\frac{R}{50 \text{ k}\Omega < R}$ $\frac{50 \text{ k}\Omega < R}{1 \text{ M}\Omega < R}$ $\frac{1 \text{ M}\Omega < R}{1 \text{ M}\Omega < R}$ $\frac{1 \text{ M}\Omega < R}{2 \text{ M}\Omega}$ $\frac{2 \text{ M}\Omega}{25 \text{ M}\Omega}$	$\begin{array}{c} < 50 \text{ k}\Omega\\ < 1 \text{ M}\Omega\\ < 2 \text{ M}\Omega\\ \end{array}$	$\begin{array}{c c} 20 & & & \\ & 0 & 20 \\ & \text{Ambient Tem} \end{array}$	e max. e max. c max. C T1 & T2 e max. e max. e max. c max. e max. e max. e max. e max. e max.
	Residual Resistance	be derated in accordance on the right.	e with the figur $\frac{R}{50 \text{ k}\Omega < R}$ $\frac{50 \text{ k}\Omega < R}{1 \text{ M}\Omega < R}$ $\frac{1 \text{ M}\Omega < R}{1 \text{ M}\Omega < R}$ $\frac{1 \text{ M}\Omega < R}{2 \text{ M}\Omega}$ $\frac{2 \text{ M}\Omega}{25 \text{ M}\Omega}$	$\begin{array}{c} < 50 \text{ k}\Omega\\ < 1 \text{ M}\Omega\\ < 2 \text{ M}\Omega\\ \end{array}$	$\begin{array}{c c} 20 & & & \\ & 0 & 20 \\ & \text{Ambient Tem} \end{array}$	e max. e max. c max. C T1 & T2 e max. e max. e max. c max. e max. e max. e max. e max. e max.
	Residual Resistance Insulation Resistance	be derated in accordance on the right. $Standard$ $Semi-standard$ $\frac{R < 2 \text{ k}\Omega}{2 \text{ k}\Omega < R < 50 \text{ k}\Omega}$ $\frac{2 \text{ k}\Omega < R < 250 \text{ k}\Omega}{R > 250 \text{ k}\Omega}$ $\frac{50 \text{ k}\Omega < R < 250 \text{ k}\Omega}{R > 250 \text{ k}\Omega}$	e with the figur $\frac{R}{50 \text{ k}\Omega < R}$ $\frac{50 \text{ k}\Omega < R}{1 \text{ M}\Omega < R}$ $\frac{1 \text{ M}\Omega < R}{1 \text{ K}}$ $\frac{2 \Omega}{2 \Omega}$ $\frac{25 \Omega}{100 \Omega}$	8 < 50 kΩ < 1 MΩ < 2 MΩ B, C, G T2 & T3 max. max. max. max.	20 Ω	e max. e max. c max. C T1 & T2 e max. e max. e max. c max. e max. e max. e max. e max. e max.
	Residual Resistance Insulation Resistance Dielectric Withstand Voltage	be derated in accordance on the right.	e with the figur $\frac{R}{50 \text{ k}\Omega < R}$ $\frac{50 \text{ k}\Omega < R}{1 \text{ M}\Omega < R}$ $\frac{1 \text{ M}\Omega < R}{1 \text{ K}}$ $\frac{2 \Omega}{2 \Omega}$ $\frac{25 \Omega}{100 \Omega}$	8 < 50 kΩ < 1 MΩ < 2 MΩ B, C, G T2 & T3 max. max. max. max.	20 Ω	e max. e max. c max. C T1 & T2 e max. e max. e max. c max. e max. e max. e max. e max.
Specifications	Residual Resistance Insulation Resistance Dielectric Withstand Voltage Noise Level Operating Life	$\begin{tabular}{lll} be derated in accordance on the right. \\ \hline \\ Standard \\ \hline \\ Semi-standard \\ \hline \\ \hline & 2 \ k\Omega < R < 2 \ k\Omega \\ \hline & 2 \ k\Omega < R < 50 \ k\Omega \\ \hline & 50 \ k\Omega < R < 250 \ k\Omega \\ \hline & R > 250 \ k\Omega \\ \hline \hline & 50 \ M\Omega \ min. \ at \ 250 \ Vdc \\ \hline & 250 \ Vac \ for \ 1 \ minute \\ \hline & 100 \ mV \ max. \\ Apply 20 \ V \ (When \ Voltag \ Rotate \ shaft \ at \ 30 \ r/min. \\ \hline \end{tabular}$	e with the figur $\frac{R}{50 \text{ k}\Omega} < R$ $1 \text{ M}\Omega < R$ $1 \text{ M}\Omega < R$ A, B, D, G $T1 \& T2$ 2Ω 25Ω 100Ω e Rating < 20	$\begin{array}{c} < 50 \text{ k}\Omega \\ < 1 \text{ M}\Omega \\ < 2 \text{ M}\Omega \\ \hline \\ B, C, G \\ T2 \& T3 \\ \hline \text{max.} \\ \hline \end{array}$	20 Ω	e max. e max. c max. C T1 & T2 e max. e max. e max. c max. e max. e max. e max. e max.

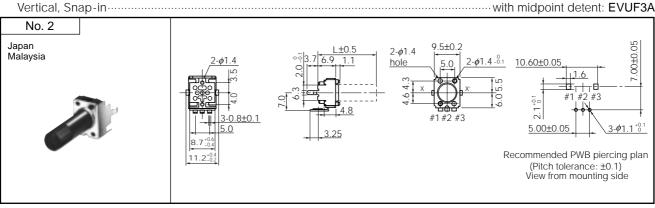
■ Dimensions in mm (not to scale)

Single Type without Bushing

without midpoint detent: EVUE20, EVUE2A, EVUE21

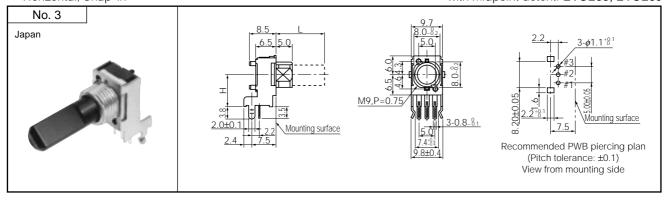


without midpoint detent: EVUF2A



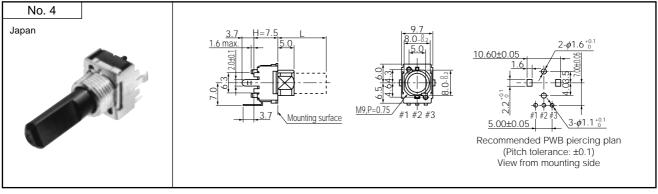
 Single Type with Bushing Horizontal, Snap-in

without midpoint detent: EVUE25, EVUE2J with midpoint detent: EVUE35, EVUE3J



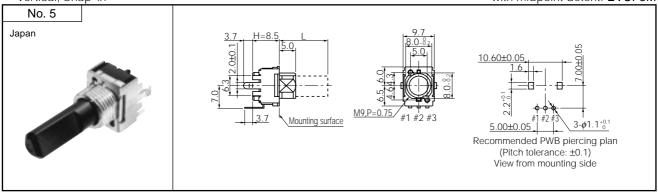
without midpoint detent: EVUF2J

Vertical, Snap-in with midpoint detent: EVUF3J



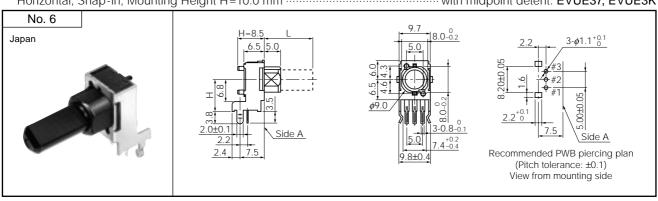
without midpoint detent: EVUF2M

Vertical, Snap-in with midpoint detent: EVUF3M

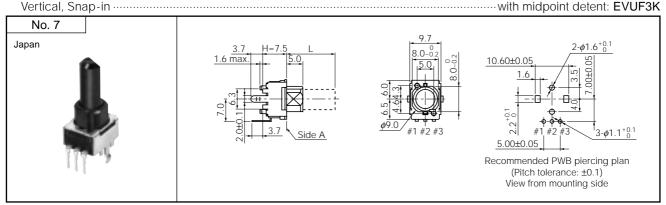


• Single Type with Sleeve Horizontal, Snap-in, Mounting Height H=10.0 mm with midpoint detent: EVUE37, EVUE3K

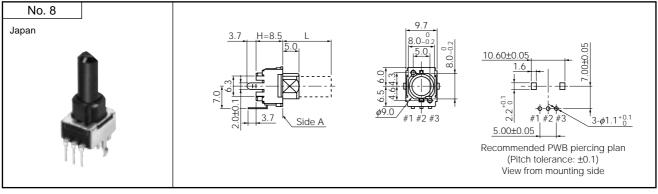
without midpoint detent: EVUE27, EVUE2K



without midpoint detent: EVUF2Kwith midpoint detent: EVUF3K



without midpoint detent: EVUF2L Vertical, Snap-in with midpoint detent: EVUF3L



• Shaft Trims and Dimensions in mm for Type without Bushing (Drawings are at full CCW position.)

Type F (Flat)

Product No. 7-8-9 th	F15	F20	F25	F30	L±0.5 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
L	15.0	20.0	25.0	30.0	ℓ±0.2 10 5 7
l	6.0	7.0	12.0	12.0	

Type E (40 teeth serrations)

Product No. 7.8.9 th	E15	E17	E20	E25	E30	E35	L±0.5
L	15.0	(17.0)	20.0	25.0	30.0	35.0	\$\lfloor \frac{\psi_0}{9}\$
l	6.0	7.0	7.0	7.0	7.0	7.0	

Type M (24 teeth serrations)

Product No. 7-8-9 th	M20	M25	M30	M35	——————————————————————————————————————
L	20.0	25.0	30.0	35.0	<u>\$\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\</u>
l	7.0	7.0	7.0	7.0	c

Type S (with screw slot)

Type 3 (Willi	SCIEW	SIOty
Product No. 7.8.9 th	S01	30%.
L	9.5	L=9.5±0.5 8 X X X
l	_	

Type H (40 teeth serrations, with screw slot)

gpo in the teem seriations, with serious stely								
Product No. 7.8.9 th	H15	H20	H25	L±0.5 \$50 A 0±0.5				
L	15.0	20.0	25.0	(±0.2 *\sigma				
l	6.0	7.0	7.0	C 25 7 10 0				

● Shaft Trims and Dimensions in mm for Types with Bushing or Sleeve (Drawings are at full CCW position.) Type F (Flat)

Type I (I lat)							
Product No. 7.8.9 th	FK1	FK3	FK4	FK5	FL3	FK6	5.0 l
L	12.5	15.0	17.5	20.0	21.5	22.5	
l	7.0	7.0	12.0	12.0	12.0	12.0	

Note: When you have special requirements other than the above, consult our salesmen.

Standard Type Slide Potentiometers

Japan Malaysia

Type: **EWAK/EWAM/EWAN EWAP/EWAQ**

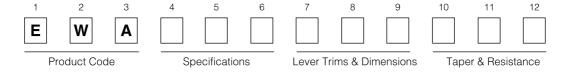
Features

- Compact size and wave-soldering available
- A large variety: 15.0, 20.0, 30.0, 45.0 and 60.0 mm travel

■ Recommended Applications

- Audio Equipment
- Video Equipment
- Home Electrical Appliances
- Electronic Musical Instruments

■ Explanation of Part Numbers



■ Product Chart

Classification		Standard	Functions						
Travel	Single/Dual	part numbers	Metal lever	Mounting screw hole	Midpoint detent	Midpoint tap	Remarks		
	Single	EWAKF	0			0			
15.0 mm	Dual	EWAKA	0			0			
20.0 mm	Single	EWAMF	0			0			
	Dual	EWAMA	0	0	0	0			
	Single	EWANF	0	0	0	0			
30.0 mm	Dual	EWANA	0	0	0	0			
	Single	EWAPF	0	0	0	0			
45.0 mm	Dual	EWAPA	0	0	0	0			
60.0 mm	Single	EWAQF	0	0	0	0			
	Dual	EWAQA	0	0	0	0			

Notes:

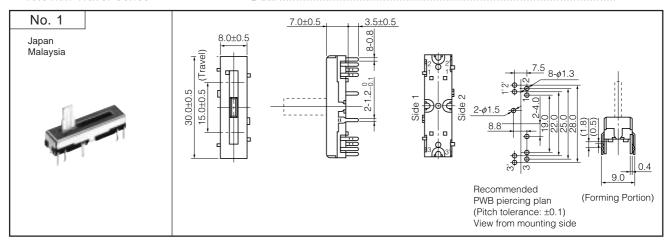
■ Minimum Quantity/Packing Unit

	EWAK	100 pcs. (Tray Pack)	
	EWAM	100 pcs. (Tray Pack)	Lever length≤ 20.0 mm
Minimum Quantity/	EVVAIVI	50 pcs. (Tray Pack)	Lever length≥ 21.0 mm
Packing Unit	EWAN	100 pcs. (Tray Pack)	
r doming offic	EWAP	50 pcs. (Tray Pack)	
	EWAQ	50 pcs. (Tray Pack)	Lever length≤ 20.0 mm
	LWAQ	25 pcs. (Tray Pack)	Lever length≥ 21.0 mm
	EWAK	1000 pcs.	
	EWAM	1000 pcs.	Lever length≤ 20.0 mm
	LVVAIVI	500 pcs.	Lever length≥ 21.0 mm
Quantity/Carton	EWAN	1000 pcs.	
	EWAP	500 pcs.	
	EWAQ	500 pcs.	Lever length≤ 20.0 mm
	LVVAQ	250 pcs.	Lever length≥ 21.0 mm

Standard part numbers are insulated lever types.

^{2.} O=available

- Dimensions in mm (not to scale)
- 15.0 mm Travel Series
- Single EWAKF
 Dual EWAKA



• 20.0 mm Travel Series

- No. 2

 Japan
 Malaysia

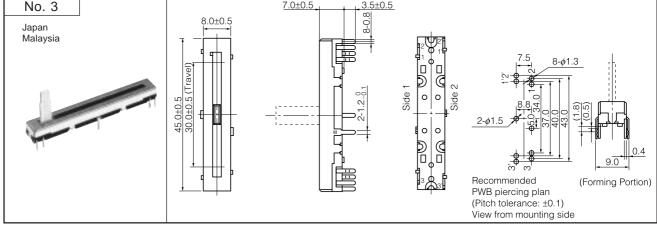
 7.0±0.5

 3.5±0.5

 Recommended
 PWB piercing plan
 (Pitch tolerance: ±0.1)
 View from mounting side

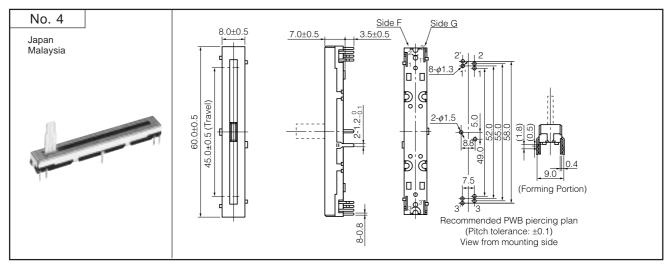
 (Forming Portion)

• 30.0 mm Travel Series



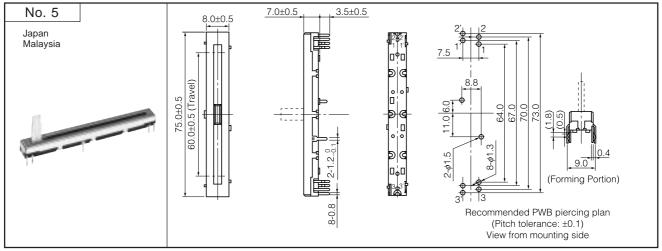
• 45.0 mm Travel Series

 Single EWAPF • Dual EWAPA



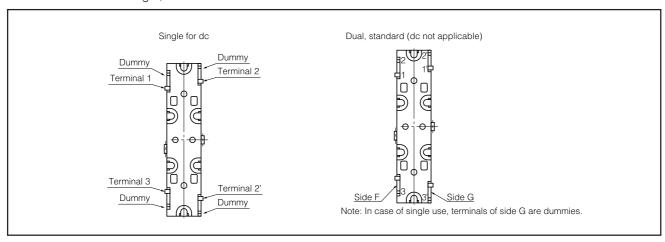
• 60.0 mm Travel Series





- 1. Refer to the drawing below for terminal alignment of single slide potentiometers.
- Slide Potentiometers with no Midpoint Tap
- Terminals 3-3' and the next inner terminals are connected together as a common terminal.
- Slide Potentiometers with Midpoint Tap
 The next inner terminals to Terminal 3-3' shall be used for midpoint taps.

Terminal Numbers of Single, dc Version



■ Lever Trims and Dimensions in mm

1. Insulated lever (15.0, 20.0, 30.0, 45.0, 60.0)

2. Metal lever (15.0, 20.0, 30.0, 45.0, 60.0)

Туре	Insulated lever	Туре	Metal lever			
С	Part No. Length 7th to 9th L	С	Part No. Length 7th to 9th L C10			
X	Part No. Length 7th to 9th	S	Part No. Length 7th to 9th L S10 10.0 7.0 S15 15.0 8.0 S20 20.0 8.0			
U	Part No. Length 7th to 9th L U10	D	Part No. Length 7th to 9th L & D15			

MediaSensor[™] Absolute, Sealed, Gage Pressure Sensors **Family Product Overview**

Product Description

The MediaSensor™ (P51) family of bulk micro-machined, absolute, sealed and gage pressure sensors are for both harsh and benign media with superior accuracy over an operating temperature of -40°C to 105°C. These compact, robust sensors measure pressures from 3 PSI to 5,000 PSI and are well suited for a variety of automotive, industrial and commercial applications.

Product Features

- **Superb Accuracy:**
 - +/- 0.5% Full Scale for 75 PSI to 5000 PSI
 - +/- 1% Full Scale for 15 PSI to 60 PSI
 - +/- 2% Full Scale for 3 PSI to 10 PSI
- Pressure Ranges: 3 PSI to 5,000 PSI
- **Electronics:**
 - 0.5 4.5 Volt output (with 5V input)
 - 0.5 4.5 Volt output with overvoltage protection (with 5V input)
 - 1-5 Volt non output (with 8 30V input)
 - 4 20 mA output (with 8 30V input)
- Temperature Range: -40°C to 105°C
- Maximum Flexibility: Custom ASIC provides signal conditioning calibration and temperature compensation.
- Standard and custom options available for OEM quantities
- **Excellent price/performance ratio**



MediaSensor™ Family of Pressure Sensors with integrated signal conditioning

- Compact, Robust Package: All laser-welded stainless steel design for optimal media isolation in compact size
- **Chemical Compatibilities:** Any gas or liauid compatible with 304L & 316L Stainless Steel. For example, Motor Oil, Diesel, Hydraulic fluid, brake fluid, water, waste water, Hydrogen, Nitrogen, and Air.
- Typical Applications: Refrigeration; Fuel Cells; Pumps; Process Control; Spraying Hydraulics; Systems; Pneumatics: Compressors: Flow: Robotics: Agriculture: Hydrogen Storage

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Website: http://ssitechnologies.com

SSI TECHNOLOGIES, INC.

Controls Division 2643 W. Court Street Janesville, WI 53548-5011

Phone: (608)758-1500 Fax: (608) 758-2491

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MediaSensor™ Absolute, Sealed, Gage Pressure Sensors **Family Product Overview**

Standard Full Scale Pressure Ranges

- **Gage:** 3, 5, 10, 15, 25, 30, 50, 60, 75, 100, 120, 130, 200, 225, 250 and 300 PSIG
- **Sealed:** 50, 100, 150, 200, 300, 400, 500, 750, 1000, 1500, 2000, 3000 and 5000 PSIS
- **Absolute:** 15, 30, 50, 65, 75, 100, 150, 200, 250, 300, 500, 750, 1000, 1500, 2000, and 3000 PSIA

Measurement Technology

In general, pressure measurement technology translates force from an induced pressure into an electrical quantity. The MediaSensor[™] family of pressure transducers and transmitters use piezoresistive technology for its sensor signal processing to measure pressure.

A micro-machined stainless steel convoluted diaphragm with a silicon crystal semiconductor is used. Strain gauges (resistive elements) in the silicon crystal are used in a Wheatstone Bridge circuit. When pressure is applied, the resistivity of the strain gauges changes proportional to the pressure applied. Since a single silicon crystal is used it has a low mechanical hysteresis with good linearity.

One leg of the bridge measures the input pressures port. The other leg of the bridge is connected to the reference port the input pressure port is compared to. The connection to this reference port determines the pressure sensing convention used.

The MediaSensor™ family comes in a choice of three pressure sensing type conventions: absolute, gauge (vented or sealed).

Absolute MediaSensors[™] measure pressure relative to perfect Vacuum pressure (0 PSI) which remains unchanged regardless of temperature, location or other ambient conditions such as weather. Absolute MediaSensors™ are calibrated to have 0.5 Vdc, 1 Vdc, or 4 mA respectively at 0 PSIA.

There are two different gauge pressure conventions -Vented Gauge and Sealed Gauge. Gauge MediaSensors™ measure pressure relative to ambient room pressure through a port that is vented (open) to the atmosphere. Gauge MediaSensors[™] are calibrated to have 0.5 Vdc, 1 Vdc, or 4 mA respectively at 0 PSIG.

Sealed MediaSensors[™] measure pressure relative to a port that is connected to a sealed perfect vacuum chamber. Sealed MediaSensors[™] are calibrated to 14.5 PSI absolute. Sealed MediaSensors™ are calibrated to have 0.5Vdc, 1 Vdc, or 4 mA respectively at 14.5 PSIA.

The MediaSensor[™] takes the two voltage output ports of the Wheatstone bridge and amplifies the Piezoresistive pressure sensors are sensitive to changes in temperature. The MediaSensor™ uses signal conditioning to compensate for temperature and calibration. The output signal is then converted into one of four forms:

- 1) 0.5 4.5 Volt ratiometric output (transducer)
- 2) 0.5 4.5 V ratiometric output with Overvoltage protection (transducer)
- 3) 1-5 volt output (transducer)
- 4) 4 20 mA output (transmitters)

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MediaSensor[™] Absolute, Sealed, Gage Pressure Sensors **Family Product Overview**

Ratiometric outputs vary as a ratio of the supply voltage.

Transmitters are very suitable in applications that use long cables. There is virtually no error from voltage drop introduced from the wire resistance when sending the signal as a current. They are also less sensitive to electromagnetic interference.

Some piezoresistive pressure transducers use only an unprotected silicon sensing element. Silicon is a brittle crystalline material, which can sometimes crack under severe cold transient environments. The MediaSensor™ pressure transducer uses an additional 316L stainless steel convoluted diaphragm with a protective non-silicone oil to protect the sensitive silicon sensing element from the harsh media and environmental conditions. The 316L stainless steel diaphragm not only provides for optimal water and chemical media isolation for the silicon crystal sensing element but can handle cold temperature transients without sustaining damage.

Under cold transient conditions and within our operating temperature range, the oil does not gel and acts as a buffer for the silicon sensing element from the extreme temperature transients found in certain applications such as refrigeration.

MediaSensor™ Compensations Features

All the compensation circuitry is internal to the MediaSensor™ pressure transducer. No external compensation modules are needed.

1) Zero balancing (Null Offset) Calibration

During manufacturing the Wheatstone Bridge resistive elements are closely matched and compensated, however an offset voltage (due to resistance differences) may still exist. SSI MediaSensor™ compensates for this offset over operating temperature range (refer to Table 1).

2) Span Calibration

The resistance of silicon gauges is temperature dependent. The span will shift with temperature to a final stabilized value as it warms up. SSI MediaSensor™ compensates for this span variation over operating temperature range.

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MediaSensor[™] Absolute, Sealed, Gage Pressure Sensors Family Product Overview

Typical Connections

The following torque limits should be used when mounting the MediaSensor™ pressure port.

Straight Thread w/O-Ring:	Recommended Torque
High Pressure (> 750 PSI)	300 in lb
All others with out Port types T, U, Y	150 in lb
Parts with Ports T,U, Y	120 in lb
NPTF Thread:	2 T.F.F.T. (Turns From Finger Tight)

MediaSensor™ 4 -20mA Output connections:

- 1) Connect the Power Lead (Red) to the + terminal of the supply voltage.
- 2) Connect the Return Lead (White) to the + terminal of the current measuring device
- 3) Connect the terminal of the current measuring device to the terminal of the supply voltage.

MediaSensor™ Voltage Output connections:

- Connect the Power Lead (Red) to the + terminal of the supply voltage.
- Connect the Ground Lead (Black) and the terminal of the supply voltage to – input of your voltage measurement equipment.
- Connect the Vout Lead (White) to the + input of your voltage measurement equipment.

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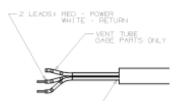
MediaSensor™ Absolute, Sealed, Gage Pressure Sensors Family Product Overview

Packaging

Wire Color

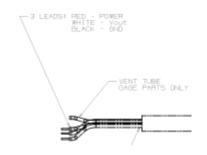
MediaSensor™ is readily available in a large selection of standard packaging options. MediaSensor™ offers an integral harness with 6 standard lengths and four standard readily available connectors (Packard, Deutsch, M12 and Mini DIN). In addition, SSI will work with the customer to meet their needs with custom options for large volumes orders. (I.e... special fittings & connectors; special pressure ranges; operating temperature; and increased accuracy).

Integral Harness (Standard lengths of 6", 12", 18", 24", 36" and 72"). The Harness can be constructed of either PVC Jacketed 18 or 24 AWG Wire.



Red - Power White - Return

Integral Harness Transmitter (4 to 20 mA)



Wire Color

Red - Power White - Vout Black - Ground

Integral Harness Transducer(1 to 5 Vdc or 0.5 to 4.5Vdc)

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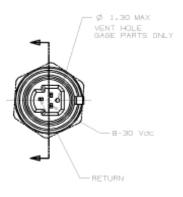






SSI Technologies – Application Note PS-AN2 MediaSensor™ Absolute, Sealed, Gage Pressure Sensors Family Product Overview

Standard Connector Options



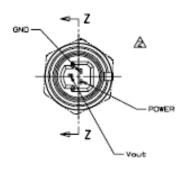
- Pin 1 Power
 - 2 Not Used
 - 3 Return

Packard Connector Transmitter (4 to 20 mA)



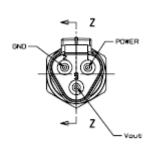
- Pin 1 Power
 - 2 Not Used
 - 3 Return

Deutsch Connector Transmitter (4 to 20 mA)



- Pin 1 Power
 - 2 Ground
 - 3 Vout

Packard Connector Transducer (1 to 5 Vdc or 0.5 to 4.5 Vdc)



- Pin 1 Power
 - 2 Ground
 - 3 Vout

Deutsch Connector Transducer (1 to 5 Vdc or 0.5 to 4.5 Vdc)

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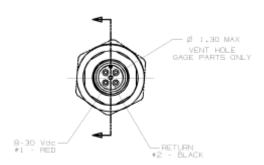
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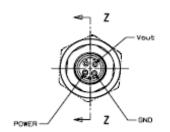
SSI Technologies – Application Note PS-AN2 MediaSensor™ Absolute, Sealed, Gage Pressure Sensors Family Product Overview





- 2 Return
- 3 Not Used
- 4 Not Used

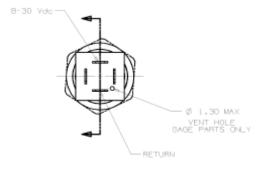
M12 Connector Transmitter (4 to 20 mA)



Pin 1 - Power

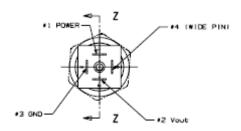
- 2 Ground
- 3 Vout
- 4 Not Used

M12 Connector Transducer (1 to 5 Vdc or 0.5 to 4.5 Vdc)



- Pin 1 Power
 - 2 Return
 - 3 Not Used
 - 4 Not Used

DIN 43650 Transmitter Connector



Pin 1 - Power

- 2 Vout
- 3 Ground
- 4 Not Used

DIN 43650 Transducer Connector

SSI TECHNOLOGIES, INC.

Controls Division 2643 W. Court Street Janesville, WI 53548-5011

Phone: (608)758-1500 Fax: (608) 758-2491

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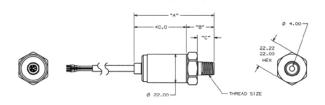




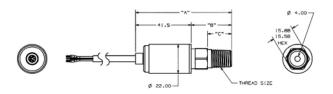


SSI Technologies – Application Note PS-AN2 MediaSensor™ Absolute, Sealed, Gage Pressure Sensors Family Product Overview

_Standard Packaging Options



THREAD SIZE	LENGTH "A"	LENGTH "B"	LENGTH "C"
1/4-18 NPT	66.6	26.0	18.0
1/8-27 NPT	61.6	21.0	13.0
M12-1.5 6g	59.6	19.0	11.0
7/16-20 UNF	59.6	19.0	11.0
3/8-24 UNF	58.1	17.5	9.5



THREAD SIZE	LENGTH "A"	LENGTH "B"	LENGTH "C"
1/4-18 NPT	72.0	30.5	18.0
1/8-27 NPT	67.0	25.5	13.0
M12-1.5 6g	65.0	23.5	11.0
7/16-20 UNF	65.0	23.5	11.0
3/8-24 UNF	63.5	22.0	9.5

Integral Harness with 22mm Hex

Integral Harness with 5/8" Hex

Harness Construction: PVC Jacketed 18 or 24 AWG Wire

Please visit our website at http://www.ssitechnologies.com for a more information and a listing of all the series of pressure sensors in the MediaSensor™ family or call SSI toll-free at 1-888-477-4320

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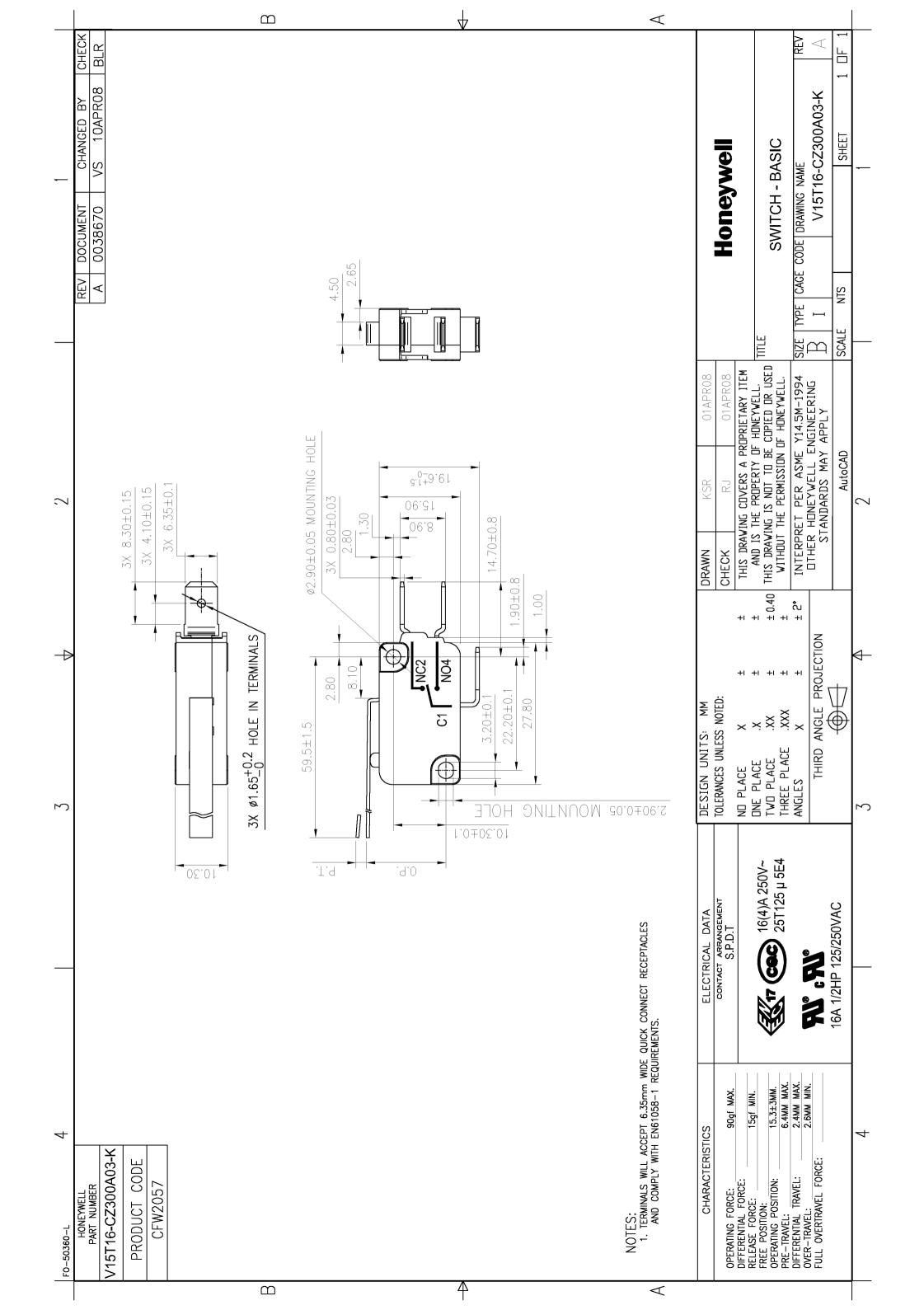
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<u>ANEXO D</u>

PLANOS



ANEXO D

PLANOS



<u>Planos</u>

Plano 1.00 → Conjunto

Plano 1.01 → Lista de elementos

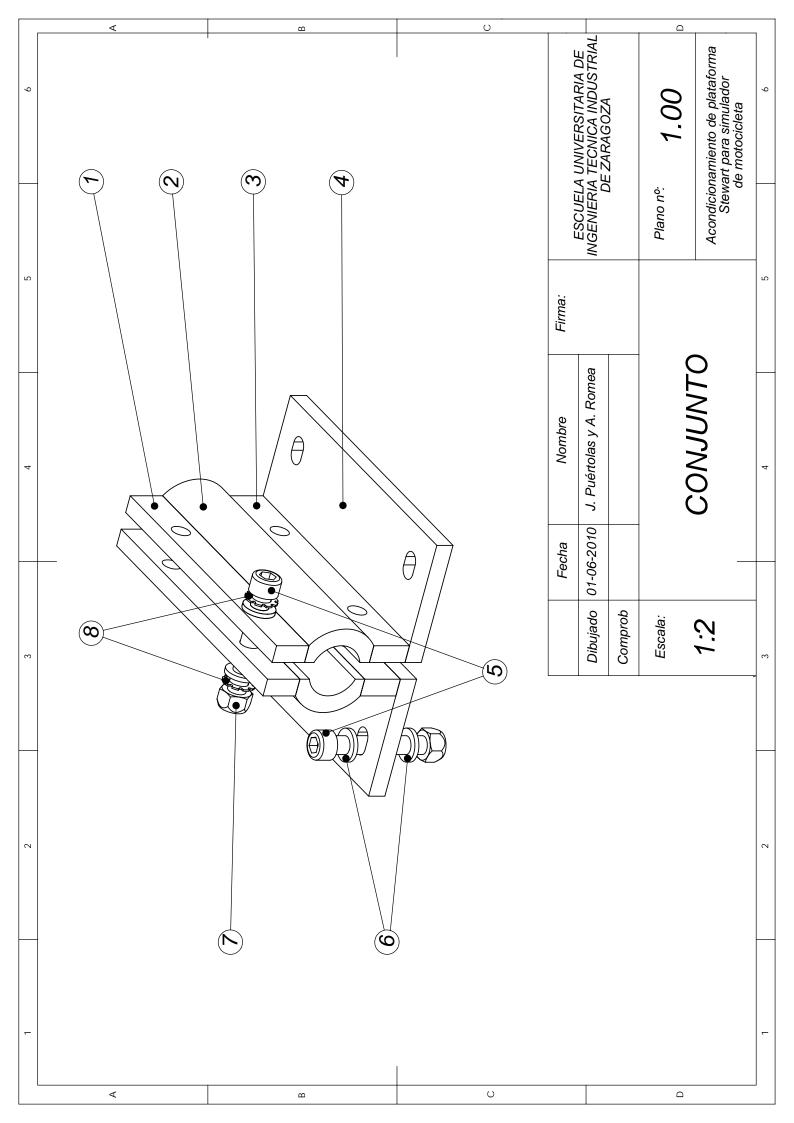
Plano 1.02 → Medio conjunto

Plano 1.03 → Pletina superior

Plano 1.04 → Pletina inferior

Plano 1.05 → Pletina base

Plano 1.06 → Zapata



		1			2		3		4	
4	Α									Α
E	33									В
	C									С
D			8	8	Arandela esti	riada Di	IN 6797	Comercial ∅ 10.5		
	О		8	7	Tuerca ISO 10513			Come	rcial M10 X 1.25 calidad 8	D
		16	6		ana ISO 8738			Comercial Ø 10		
			8	5	Tornillo ISO 4762			Comer	cial M10 X 60 calidad 12.9	
			2	4	Pletina base			F-1140		
			2	3		inferio	r		F-1140	
E		2	2		Zapata			F-1140		
		2 1		Pletina superior		or		F-1140	E	
		Nº Piezas	Nº Pieza	Designación y	observ	raciones		Materiales y medidas		
				Fecha	Nombre		Firma:			
F			Dibujado	01-06-2010	J. Puértolas y A. Ro	mea		ESC INGEN	UELA UNIVERSITARIA DE IERIA TECNICA INDUSTRIA DE ZARAGOZA	-
			Comprob						DE ZANAGUZA	
	=		Escala:		LISTA	ISTA DE		Pland	0 nº: 1.01	F
			S/E		ELEMEN				dicionamiento de plataforma Stewart para simulador de motocicleta	
		1			2		3		4	

